

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace, without prejudice, all prior versions, and listings, of claims in the application.

Listing of Claims:

Claims 1-18 (canceled).

19. (Currently Amended) A wiper device for a window of a motor vehicle, the wiper device comprising:

a wiper blade;

a mechanical system to drive the wiper blade; and

a control device to compensate for changes in clearances of the mechanical system as a function of at least one of load changes and a service life of the mechanical system.

20. (Currently Amended) The wiper device of claim 19, wherein the control device compensates for the changes in clearances as a function of the service life.

21. (Currently Amended) The wiper device of claim 19, further comprising an electronically reversible drive, wherein the mechanical system is operable to rotatably move the wiper blade via the electronically reversible drive between an upper wiper blade end position and a lower wiper blade end position associated with two drive end positions;

wherein, to compensate for the changes in clearances, the control device is operable to change the two drive end positions for at least one of as a number of load changes increases and as the service life of the mechanical system increases.

22. (Previously Presented) The wiper device of claim 19, wherein the service

life of the mechanical system is determined by a distance traveled by the motor vehicle.

23. (Previously Presented) The wiper device of claim 19, wherein the control device is operable to compensate incrementally one of every 50,000 to 200,000 wiper periods and every 50,000 to 200,000 load changes.

24. (Previously Presented) The wiper device of claim 22, wherein the control device is operable to compensate incrementally every 2,000 to 10,000 km.

25. (Previously Presented) The wiper device of claim 19, wherein the control device is operable to compensate continuously one of prior and subsequent to each wiping period.

26. (Previously Presented) The wiper device of claim 21, wherein the control device is operable to compensate only at a drive end position corresponding to the upper wiper blade end position.

27. (Previously Presented) The wiper device of claim 19, wherein the control device is operable to compensate as a function of a velocity of a motion of the mechanical system.

28. (Currently Amended) A method for controlling a wiper device of a motor vehicle, the method comprising:

driving a wiper blade via a mechanical system driven by an electronically reversible drive; and

compensating for changes in clearances of the mechanical system as a function of one of load changes and a service life of the mechanical system.

29. (Currently Amended) The method of claim 28, wherein the changes in

clearances are compensated as a function of the service life.

30. (Currently Amended) The method of claim 28, wherein:

the mechanical system rotatably drives the wiper blade between an upper and a lower wiper blade end position associated with two drive end positions and defining a swing angle; and

a control device compensates for the changes in clearances by changing the drive end positions at least one of as a number of load changes increase and as the service life of the mechanical system increases.

31. (Previously Presented) The method of claim 30, wherein the service life of the mechanical system is determined by a distance traveled by the motor vehicle.

32. (Previously Presented) The method of claim 30, wherein the control device compensates incrementally one of every 50,000 to 200,000 wiper periods and every 50,000 to 200,000 load changes.

33. (Previously Presented) The method of claim 31, wherein the control device compensates incrementally every 2,000 to 10,000 km.

34. (Previously Presented) The method of claim 30, wherein the control device compensates continuously one of prior and subsequent to each wiping period.

35. (Previously Presented) The wiper device of claim 30, wherein the control device compensates only at a drive end position corresponding to the upper wiper blade end position.

36. (Previously Presented) The method of claim 30, wherein the control

device compensates as a function of a velocity of a motion of the mechanical system.

37. (Previously Presented) The wiper device of claim 19, wherein the control device is operable to compensate incrementally one of every 100,00 wiper periods and every 100,000 load changes.

38. (Previously Presented) The wiper device of claim 22, wherein the control device is operable to compensate incrementally every 5,000 km.

39. (Previously Presented) The method of claim 30, wherein the control device compensates incrementally one of every 100,000 wiper periods and every 100,000 load changes.

40. (Previously Presented) The method of claim 31, wherein the control device compensates incrementally every 5,000 km.